

#### Petri nets

#### Idea

- Formal representation of concurrent systems
- Formal model and graphical representation are equivalent in classical Petri nets

#### Remarks

- Developed by Carl Adam Petri, 1962
- Many variations and extensions
- Here: Application for modeling business processes and their analysis

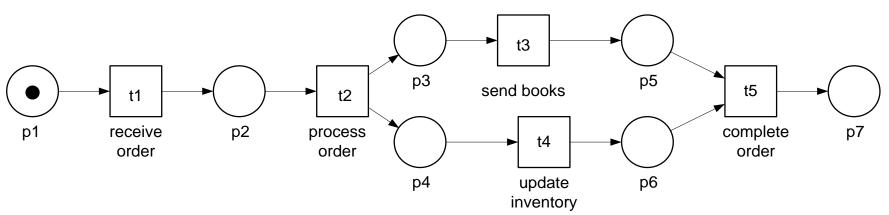


#### Petri nets

#### Characterization

- Petri net is a directed graph consisting of places, transitions and directed edges between them
- Petri nets are bipartite graphs, i.e., edges between two places and edges between two transitions are not allowed

#### Example Petri net



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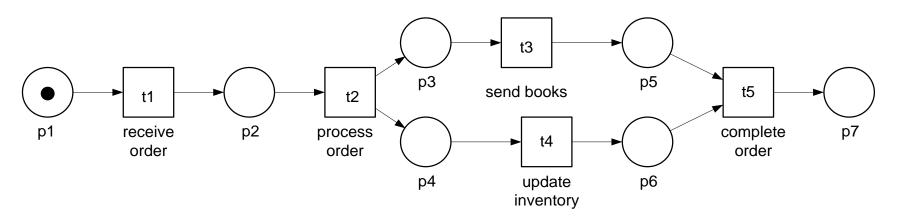
### **Definition Petri net**

#### **Definition 4.1** A Petri net is a tuple (P, T, F) with

- a finite set P of places
- a finite set T of transitions such that  $T \cap P = \emptyset$
- a flow relation  $F \subseteq (P \times T) \cup (T \times P)$
- A place  $p \in P$  is an input place of a transition  $t \in T$ , if and only if there exists a directed arc from p to t, i.e., if and only if  $(p, t) \in F$ . The set of input places for a transition t is denoted  $\bullet t$ .
- A place p is an output place of a transition t, if and only if there exists a directed arc from t to p, i.e., if and only if  $(t,p) \in F$ . The set of output places for a transition t is denoted  $t \bullet$ .
- p• and •p denote the set of transitions that share p as input places or output place, respectively.

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$$P = \{p1, p2, p3, p4, p5, p6, p7\},\$$

$$T = \{t1, t2, t3, t4, t5\},\$$

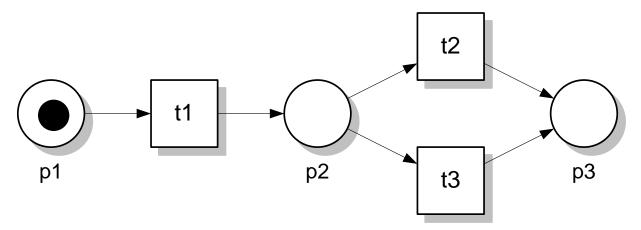
$$F = \{(p1, t1), (t1, p2), (p2, t2), (t2, p3), (t2, p4), (p3, t3), (p4, t4), (t3, p5), (t4, p6), (p5, t5), (p6, t5), (t5, p7)\}.$$

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# **Marking**

- The dynamic behavior of a system is represented by tokens in the Petri net
- The state of a Petri net (marking) is described by the distribution of tokens on places



**Definition 4.2** The marking (or state) of a Petri (P, T, F) net is defined by a function  $M: P \to \mathbb{N}$  mapping the set of places onto the natural numbers, where  $\mathbb{N}$  is the set of natural numbers including zero.



### **Condition Event Nets**

- Idea
  - Places represent conditions
  - Transitions represent events
- Consequences
  - A condition is fulfilled IFF a token is in the place
  - At any time, any place holds at most one token



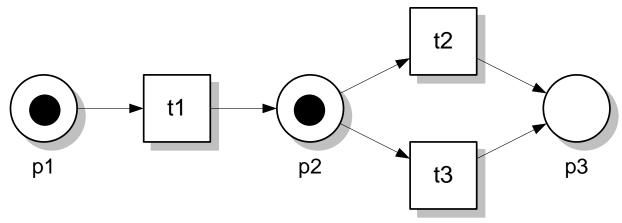
### **Execution Semantics**

#### Firing transitions

- Transitions can fire when they are enabled
- Transitions are enabled when every input place contains one token
- Firing a transition removes one token from each input place and puts a token on each output place

#### Note

Different classes of Petri nets have different firing rules





## **Definition: Condition Event Net**

**Definition 4.4** A Petri net (P, T, F) is a condition event net, if  $M(p) \leq 1$  for all places  $p \in P$  and for all states M.

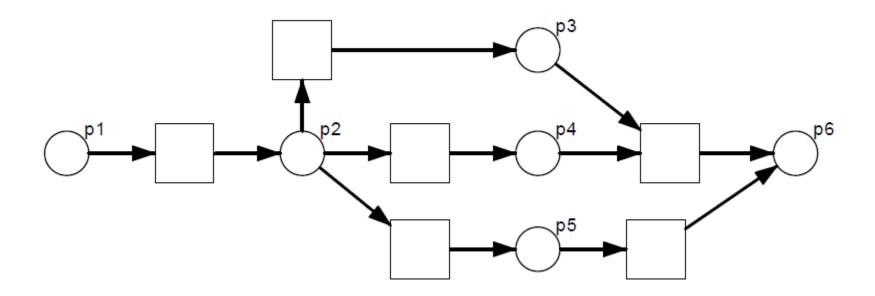
- A transition t is enabled in a state M if M(p) = 1 for all input places p of t and M(q) = 0 for all output places q of t that are not input places at the same time.
- The firing of a transition t in a state M results in state M', where

$$(\forall p \in \bullet t)M'(p) = M(p) - 1 \land (\forall p \in t \bullet)M'(p) = M(p) + 1$$

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# **Enablement and Reachability**



#### HPI Hasso Plattner Institut

# Definition: Enablement and Reachability

**Definition 4.3** Let (P, T, F) be a Petri net and M a marking. The firing of a transition is represented by a state change of the Petri net.

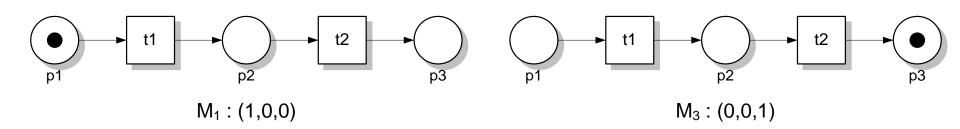
- $M \xrightarrow{t} M'$  indicates that by firing t the state of the Petri net changes from M to M'.
- $M \to M'$  indicates that there is a transition t such that  $M \xrightarrow{t} M'$ .
- $M_1 \stackrel{*}{\to} M_n$  means that there is a sequence of transitions  $t_1, t_2, \dots t_{n-1}$  such that  $M_i \stackrel{t_i}{\to} M_{i+1}$ , for  $1 \le i < n$ .
- A state M' is reachable from a state M, if and only if  $M \stackrel{*}{\to} M'$ .

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### **Execution Semantics**

- A Petri net system is a pair (PN,M) with
  - Petri net PN = (P,T,F)
  - Initial Marking M
- Let (({p1,p2,p3}, {t1,t2}, {(p1,t1), (t1,p2), (p2,t2), (t2,p3)}),(1,0,0)) be a Petri net system
  - $M_1 \stackrel{o}{\rightarrow} M_3$  where  $o=(t_1t_2)$  transfers Petri net from Marking  $M_1$  to Marking  $M_3$

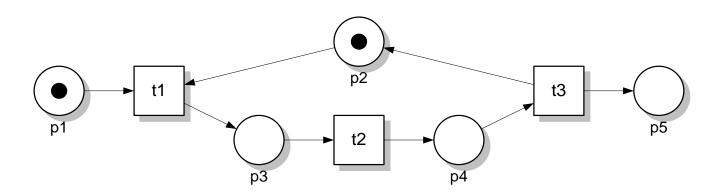




## Reachability

#### Example

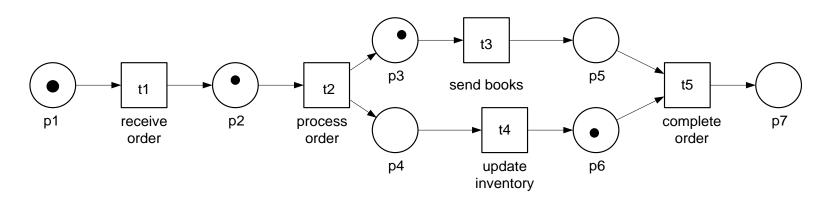
- (0,1,0,0,1) is reachable from (1,1,0,0,0) via o=(t1,t2,t3)
- (0,1,1,0,0) is not reachable from (1,1,0,0,0) because there is no corresponding sequence of transition firing





### **Process Instances in Petri Nets**

- Idea
  - Each process instance is represented by a set of tokens
  - Each token belongs to exactly one process instance
- Problems of classical Petri nets
  - Tokens are not distinguishable
  - Several process instances represented by a Petri net, but C / E nets do not allow independent process progress





### **Place/Transition Nets**

- Idea
  - In each place, an arbitrary number of tokens can reside
  - The output places of an enabled transition may contain tokens
  - Thus, several process instances in a Petri net can be represented
    - What further condition must be met?
  - Edges can be weighted; the firing behavior of transitions depends on the edge weights
- Place/Transition nets
  - Allow many tokens in a place
  - True extension of C/E nets



### **Place/Transition Nets**

**Definition 4.5**  $(P, T, F, \omega)$  is a place transition net if (P, T, F) is a Petri net and  $\omega : F \to \mathbb{N}$  is a weighting function that assigns a natural number to each arc, the weight of the arc.

The dynamic behaviour of place transition is defined as follows:

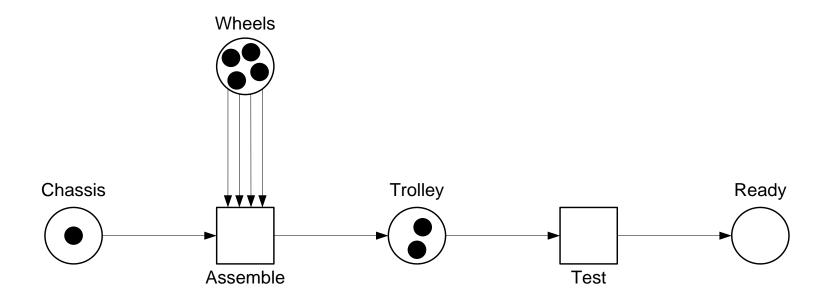
- A transition t of a place transition net is *enabled* if each input place p of t contains at least the number of tokens defined as the weight of the connecting arc, i.e., if  $M(p) \ge \omega((p,t))$ .
- When a transition t fires, the number of tokens withdrawn from its input places and the number of tokens added to its output places are determined by the weights of the respective arcs.
- From each input place p of t,  $\omega((p,t))$  tokens are withdrawn and  $\omega((t,q))$  tokens are added to each output place q.
- The firing of a transition t in a state M results in state M', where

$$(\forall p \in \bullet t) M'(p) = M(p) - \omega((p, t)) \land (\forall p \in t \bullet) M'(p) = M(p) + \omega((t, p))$$

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# **Place/Transition Nets: Example**





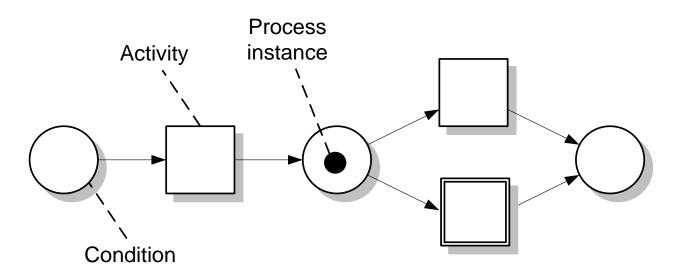
### **Workflow Nets**

- Idea
  - Using Petri nets to model business processes
- Illustration of concepts
  - Transitions represent activities
  - Places represent states
  - Edges represent the control flow
  - Tokens can carry structured values
  - Process instances' behavior is represented by firing rules



## **Example Workflow Net**

- Activities, conditions, process instances
- Nested activities represented by transitions with double border
- Beispiel
  - XOR-Split expressible by classical firing rule of transitions



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### **Workflow net: Characterization**

- A Workflow net is a Petri net with
  - A specific input place i (the initial place)
  - A specific output place o (the final place)
  - For i, no incoming edges as well as o has no outgoing edges

#### Remarks

- A token in i represents a not-yet started process instance
- A token in o represents a terminated process instance
- Each process instance is represented by a token flow from i to o



## **Workflow Nets: Definition**

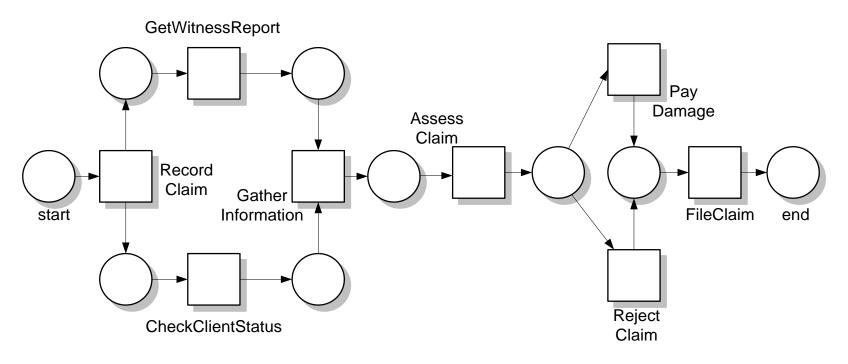
**Definition 4.8** A Petri net PN = (P, T, F) is called *workflow net*, if and only if the following conditions hold:

- There is a distinguished place  $i \in P$  (called initial place) that has no incoming edge, i.e.,  $\bullet i = \emptyset$ .
- There is a distinguished place  $o \in P$  (called final place) that has no outgoing edge, i.e.,  $o \bullet = \emptyset$ .
- Every place and every transition is located on a path from the initial place to the final place.

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# **Example Workflow Net**



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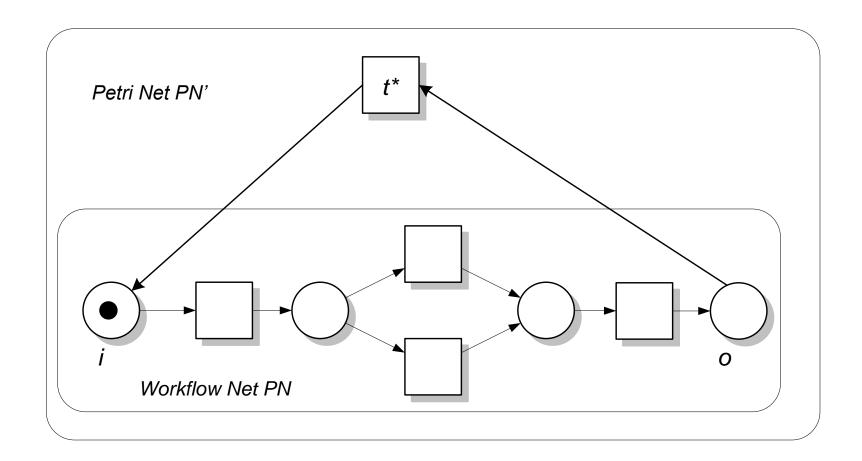
# **Properties of Workflow Nets**

- i is the only initial place: If PN is a Workflow net with initial place i, for all p ∈ P: •p ≠ Ø or p = i
- 2. o is the only final place: If PN is a Workflow net with final place o, for all  $p \in P$ :  $p \in \neq \emptyset$  or p = o
- 3. Let PN be a Workflow net. If we add a transition t\*, which connects o to i (i.e. ●t\* = {o} and t\*●= {i}), the resulting Petri net is strongly connected
- Remark

 A Petri net is strongly connected if for any pair of nodes x,y a path from x to y exists.



## **Workflow Nets: Property 3**

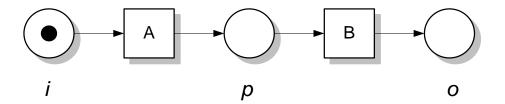


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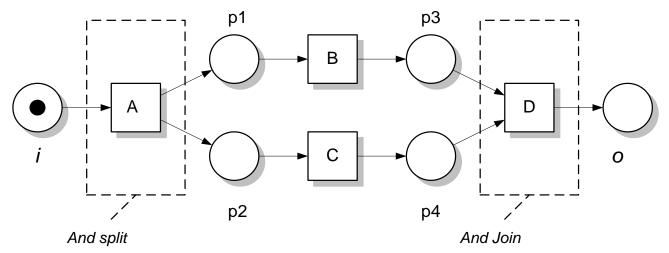


## **Control Structures in Workflow Nets**

Sequence



AND Split / AND Join



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## **Analysis of Workflow Nets**

- Idea
  - Generic structural correctness criteria for workflow nets.
  - Undesirable behavior of process instances is thus excluded

#### Basics

- Reachability analysis: Which states can be reached?
- What properties do these states possess?



## Reachability

- Idea
  - A Petri net system determines the reachable states
- Hint
  - Communication with the environment is not considered here
- Representation of the reachability graph
  - Nodes represent states
  - Edges represent state transitions, by firing transitions
  - Multiple outgoing edges: non-deterministic behavior
- Naïve technique
  - Manual creation of the reachability graph and analysis

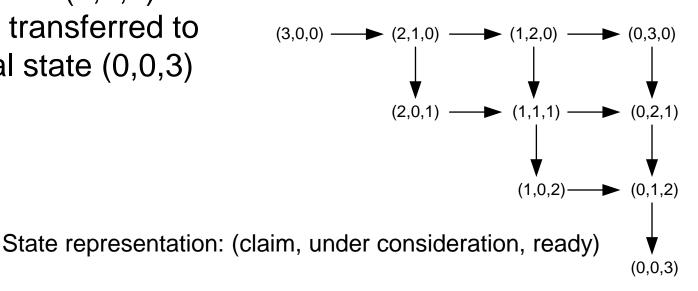


# Example(1)

claim record under consideration ready send letter

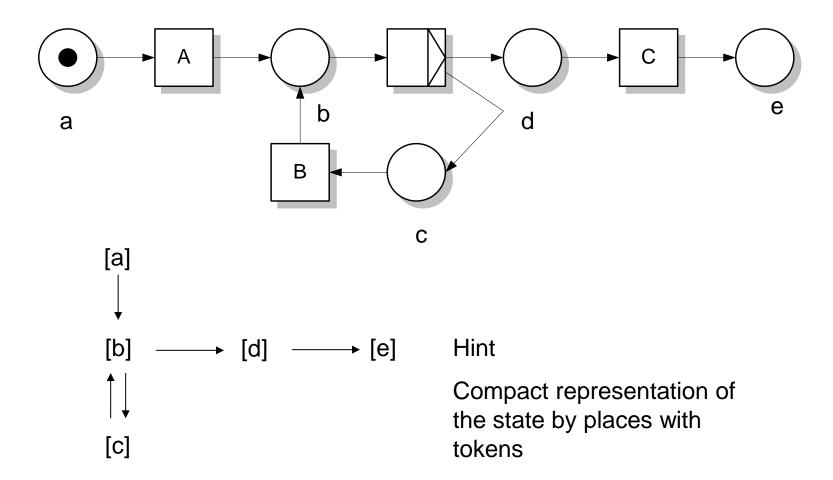
pay

 Initial state (3,0,0) is always transferred to the final state (0,0,3)



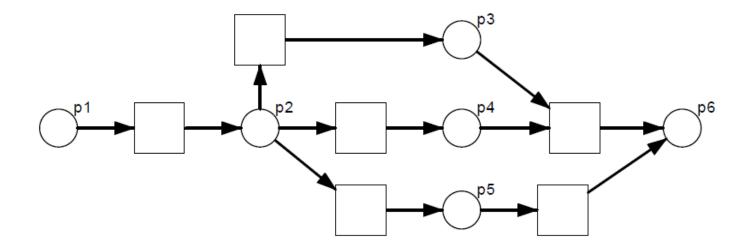


# Example (2)





# **Enablement and Reachability**





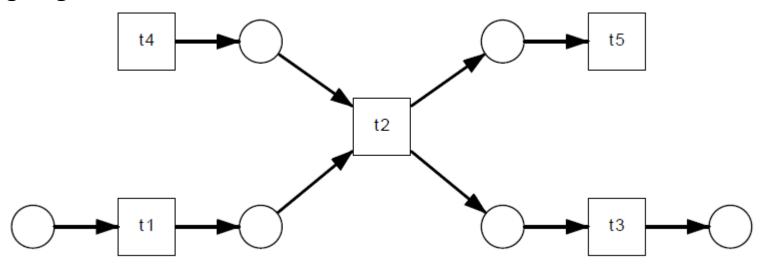
# **Structural Analysis**

- Idea
  - Structural analysis of Workflow nets to find errors
- Error possibilities
  - Transitions without in-output places
  - Transitions that can never fire (dead transitions)
  - Deadlocks, which prevent the process progress
  - Endless loops (livelock)
  - Activities that are performed after the end of the process

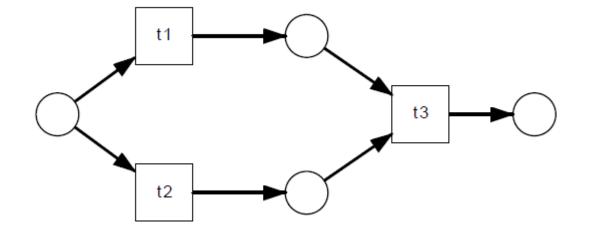


## **Structural Errors**

Dangling tasks



Deadlock

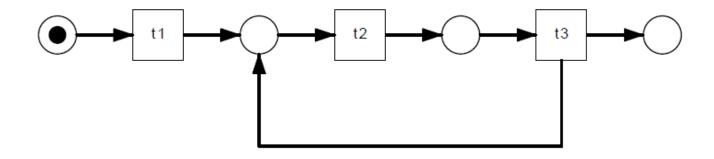


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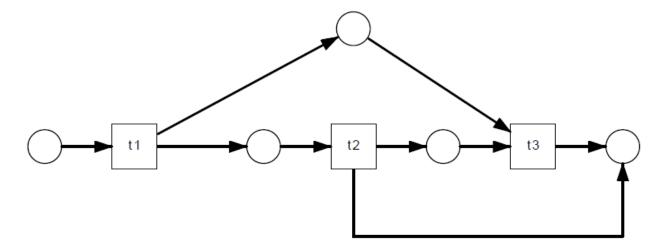


## **Structural Errors**

Livelock



Remaining Tokens



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# **Soundness-Property**

- Soundness
  - (1) For each token on the initial place exactly one token appears eventually on the final place
  - (2) If a token appears on the final place, all other places are empty
  - (3) Each transition can be enabled
- Soundness based on fairness assumption
  - Each possible decision is finally met
  - Consequence
    - No transition starvation
    - · Based on this assumption, the behavior of CPN is simulated



### **Definition**

**Definition 6.2** (States o,i and Relations  $\geq,>$ ) Let PN=(P,T,F) be a workflow net,  $i\in P$  its start place and  $o\in P$  its end place and M,M' markings.

- o is the state in which there is exactly one token in place  $o \in P$  and no tokens in any other place of the workflow net
- i is the state in which there is exactly one token in place  $i \in P$  and no token in any other place of the workflow net
- $M \geq M'$ , if and only if  $M(p) \geq M'(p), \forall p \in P$
- M > M', if and only if  $M \ge M' \land \exists p \in P : M(p) > M'(p), p \in P$

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## **Soundness: Definition**

**Definition 6.3** A workflow system (PN, I) with a workflow net PN = (P, T, F) is *sound*, if and only if

• For every state M reachable from state i there exists a firing sequence leading from M to o, i.e.,

$$\forall M(i \stackrel{*}{\to} M) \implies (M \stackrel{*}{\to} o)$$

• State o is the only state reachable from state i with at least one token in place o, i.e.,

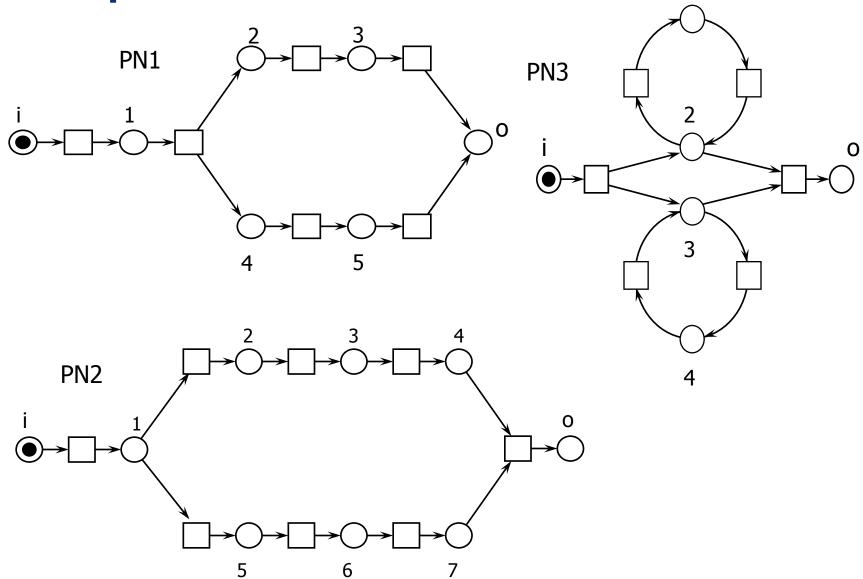
$$\forall M(i \xrightarrow{*} M \land M \ge o) \implies M = o$$

• There are no dead transitions in the workflow net in state i, i.e.,

$$(\forall t \in T) \; \exists M, M' : i \xrightarrow{*} M \xrightarrow{t} M'$$

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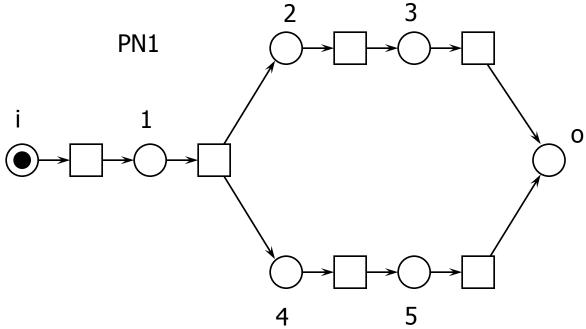


### Soundness

- Check with Reachability analysis
  - Construction of reachability graph with initial state i
- Check Procedure
  - (1) Check if there is a path from any node to o
  - (2) Check if only in a state o at least one token is only in place o
  - (3) Check if every transition occurs in the reachability graph

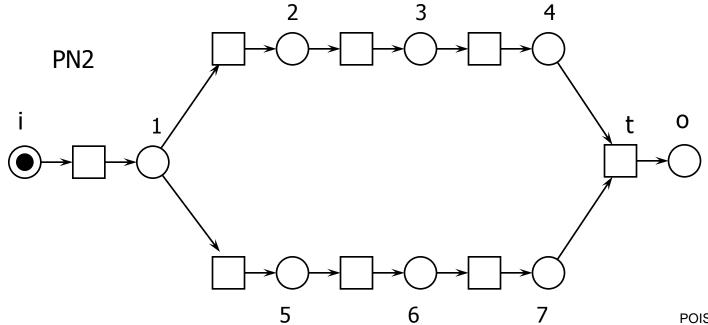


- PN1 ist not sound
  - After reaching the final place o, there are remaining tokens in the net
  - The reachable state (0,0,0,0,1,0,1) [Format: (i,1,2,3,4,5,o)] vioaltes condition (2)





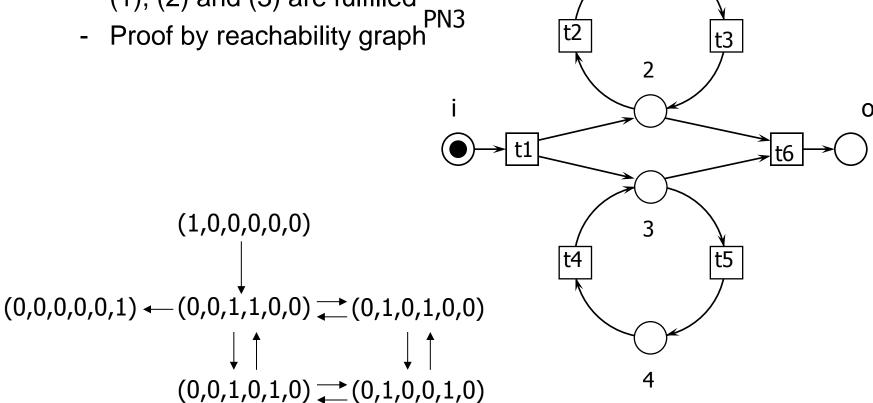
- PN2 is not sound
  - No termination
  - State (0,0,0,0,0,0,1,0) is Deadlock-state, violating condition (1)
  - Transition t can never fire, violating condition (3)



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- PN3 sound
  - (1), (2) and (3) are fulfilled



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#### Relaxed Soundness



#### Observation

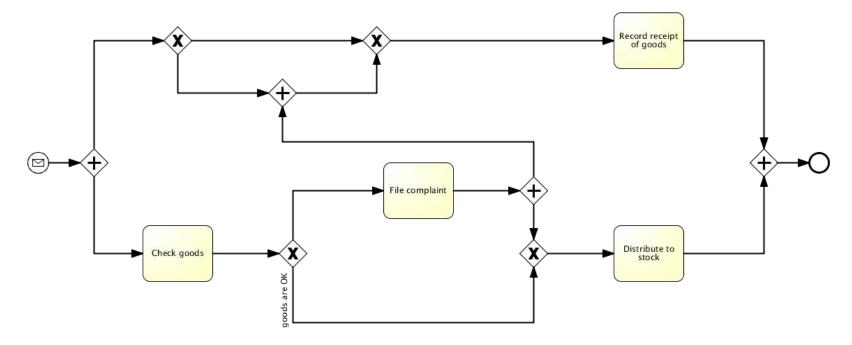
- Soundness is very strong criterion that is not appropriate in every case
- Some times a high degree of freedom in the modeling process is needed
  - This can lead to processes that are not sound
  - Nevertheless, it is meaningful to verify

#### • Idea

- Weakening soundness so that not all process instances must be sound, but every transition is involved in at least one process instance which is sound.

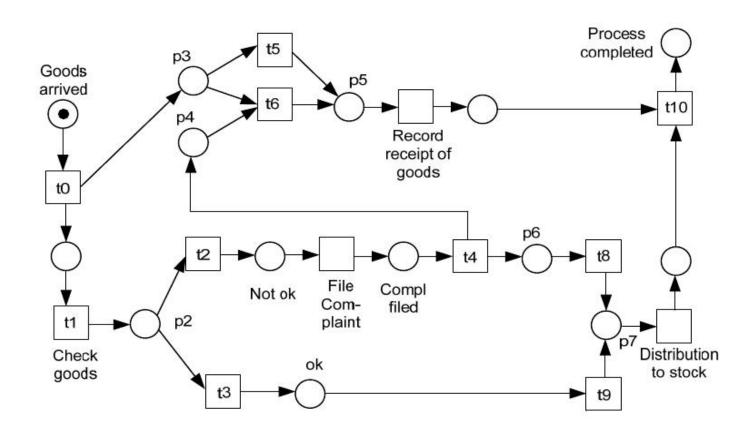


## **Motivation**



- Process instances can run into deadlocks
- Yet, each task participates in a sound execution







#### **Definition** Relaxed Soundness

**Definition 6.6** Let S = (PN, i) be a workflow system. Let  $\sigma, \sigma'$  be firing sequences and let M, M' be states.  $\sigma$  is a sound firing sequence if it leads to a state from which a continuation to the final state o is possible:  $i \xrightarrow{\sigma} M$  and  $\exists \sigma'$  such that  $M \xrightarrow{\sigma'} o$ .

**Definition 6.7** A workflow system S = (PN, i) is relaxed sound if and only if each transition of PN is an element of some sound firing sequence:

$$\forall t \in T \ \exists M, M' : (i \xrightarrow{*} M \xrightarrow{t} M' \xrightarrow{*} o)$$



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