



Name:----- ID: -----

**Q(1) True or false questions:**

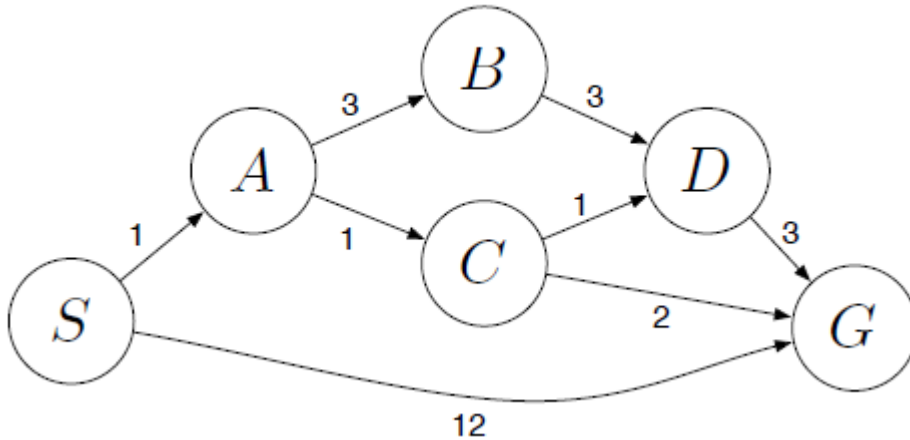
- a. ( T / F) Greedy graph search is guaranteed to return an optimal solution.
- b. (T/ F) A\* graph search is guaranteed to return an optimal solution.

Let  $h_1(n)$  be an admissible A\* heuristic. Let  $h_2(n) = 2h_1(n)$ . Then:

- c. (T / F) The solution found by A\* tree search with  $h_2$  is guaranteed to be an optimal solution.
- d. (T / F) The solution found by A\* tree search with  $h_2$  is guaranteed to have a cost at most twice as much as  $h_1$

**Q(2)** Iterative deepening is sometimes used as an alternative to breadth first search. Give one advantage and one disadvantage of iterative deepening as compared with BFS.

**Q(4)** Consider the following search space where S is the start state and G is the goal state:



- Each edge is labeled by the cost to traverse that edge.
- An estimate to the goal is given by

Node	S	A	B	C	D	G
h	4	2	6	1	3	0

- For nodes on the same level assume alphabetical order in blind search.
- Show the order of the states visited (include the repeated) and the path to the goal by:

a. The Breadth First algorithm.

Visited states:  
 Path to Goal:

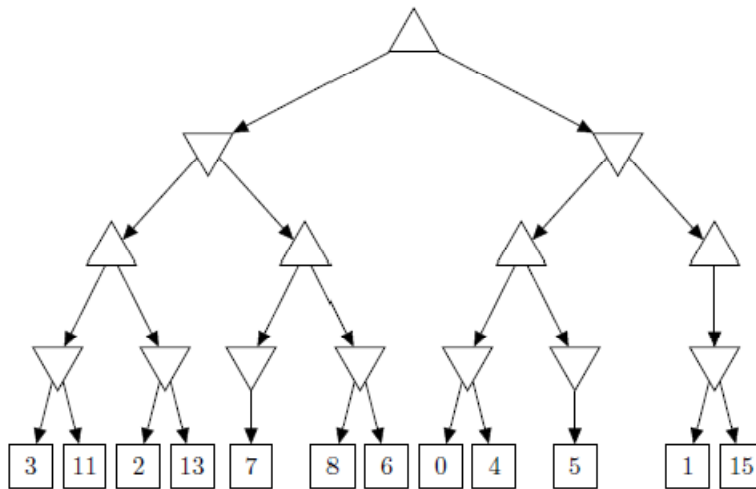
b. The Depth First algorithm.

Visited states:  
 Path to Goal:

- c. A\*
- Visited states:
- Path to Goal:
- d. Is the  $h$  used above admissible or not? Why?

**Q(3)** Develop a PEAS description of the automated taxi-driver.

**Q(5)** On the minimax game tree below, assuming its **max**'s turn to play. Cross out the branches removed by alpha-beta pruning assuming left to right traversal.



**Best Wishes**  
**Areeg Abdalla**